

Construction and implementation of multivariate dispersion models

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Introduction

- Generalized linear models: usual in statistical modelling;
→ *mostly univariate cases*.
- Multivariate frameworks for GLM are still rare.
- Most multivariate techniques are based on the Multivariate Normal distribution;
 - Suitable only for continuous and symmetrical data.
- Statistical models are realistic when can describe the dependency structure, when it exists (Temporal, Spatial, Genetic, Longitudinal, etc.)
- We can be interested in more than one response variable, possibly correlated.

The main goals of this work are to:

- Build probability distributions for multivariate, non-normal random variables and its regressions models;
 - discrete, strong asymmetrical and heavy tailed data.
- Implement the models in R [3].

Methods and Materials

Methods

The generalization of a **dispersion model** is defined as

$$p(y; \mu, \sigma^2) = a(y; \sigma^2) \exp \left\{ -\frac{1}{2\sigma^2} d(y; \mu) \right\}, \quad y \in C, \quad (1)$$

where $a \geq 0$ is an adequate function, C is the smallest interval containing the realizable values of y , d is a unit deviance in $C \times \Omega$, $\mu \in \Omega$ and $\sigma^2 \in \mathbb{R}_+$.

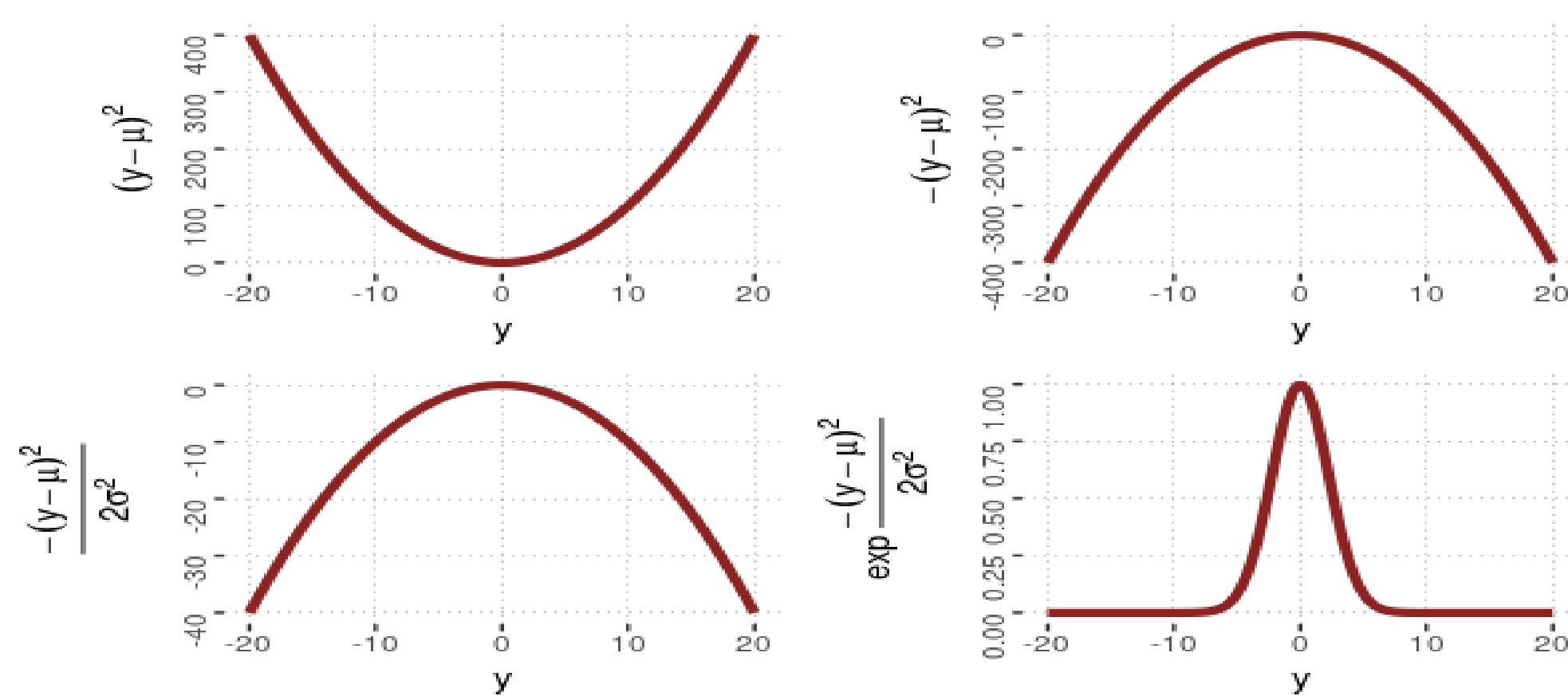


Figure 1: Core of a normal distribution, that can be generalized by a the equation of a dispersion model.

In [1], Jørgensen introduced the theory of the dispersion models, that are based on deviance residuals, a function that satisfies

$$d(y; y) = 0 \quad \forall y \in \Omega, \text{ and } d(y; \mu) > 0 \quad \forall y \neq \mu. \quad (2)$$

being Ω the parametric space for μ , $\Omega \subseteq \mathbb{R}$. The multivariate extension of the dispersion model was proposed in [2], and has the form

$$p(\mathbf{y}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = a(\mathbf{y}; \boldsymbol{\Sigma}) \exp \left\{ -\frac{1}{2} t(\mathbf{y}; \boldsymbol{\mu})^\top \boldsymbol{\Sigma}^{-1} t(\mathbf{y}; \boldsymbol{\mu}) \right\}, \quad (3)$$

where $\boldsymbol{\mu} \in \Omega$ is a open interval in \mathbb{R}^p , $\boldsymbol{\Sigma}$ is a positive-definite symmetric matrix $p \times p$, and $t(\mathbf{y}; \boldsymbol{\mu})$ is a vector of deviance residuals, given by

$$t(\mathbf{y}; \boldsymbol{\mu}) = \text{sign}(\mathbf{y} - \boldsymbol{\mu}) \sqrt{d(\mathbf{y}; \boldsymbol{\mu})},$$

and $t(\boldsymbol{\mu}; \boldsymbol{\mu}) = \mathbf{0}$, for $\boldsymbol{\mu} \in \Omega$.

Results

- Construction of non-normalized distributions and characterizing them.
- Parameter interpretation.

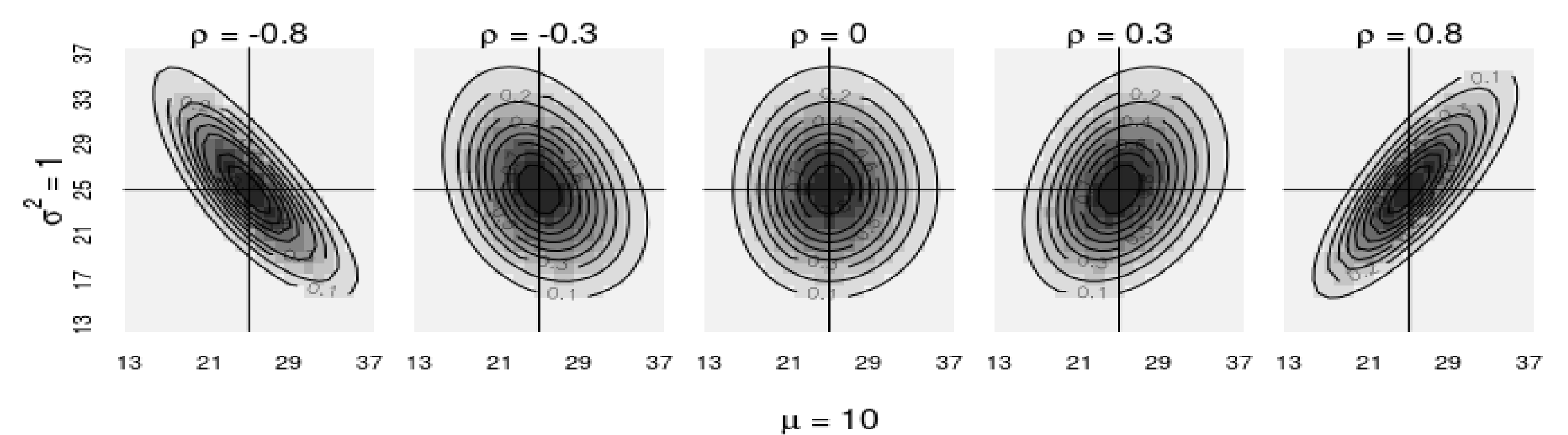


Figure 2: Core of the non-normalized bivariate Binomial distribution.

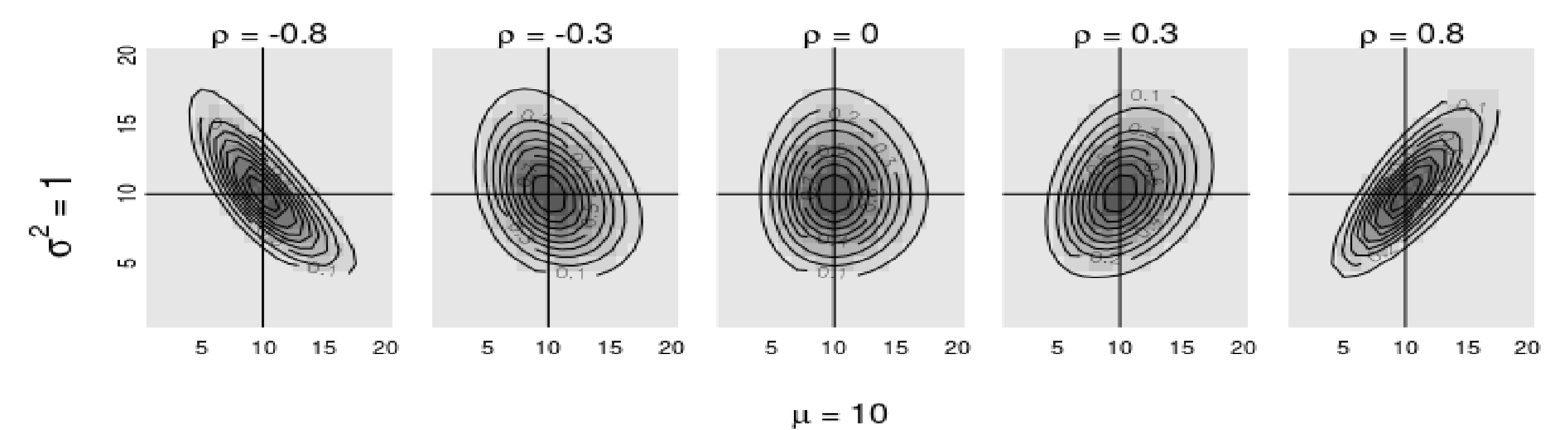


Figure 3: Core of the non-normalized bivariate Poisson distribution

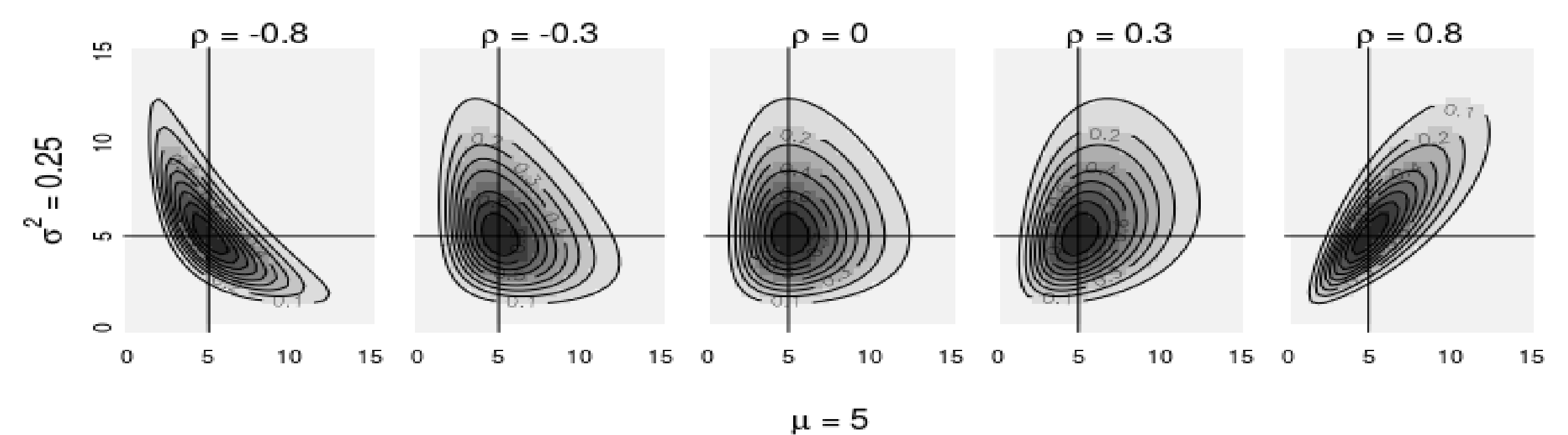


Figure 4: Core of the non-normalized bivariate Gamma distribution.

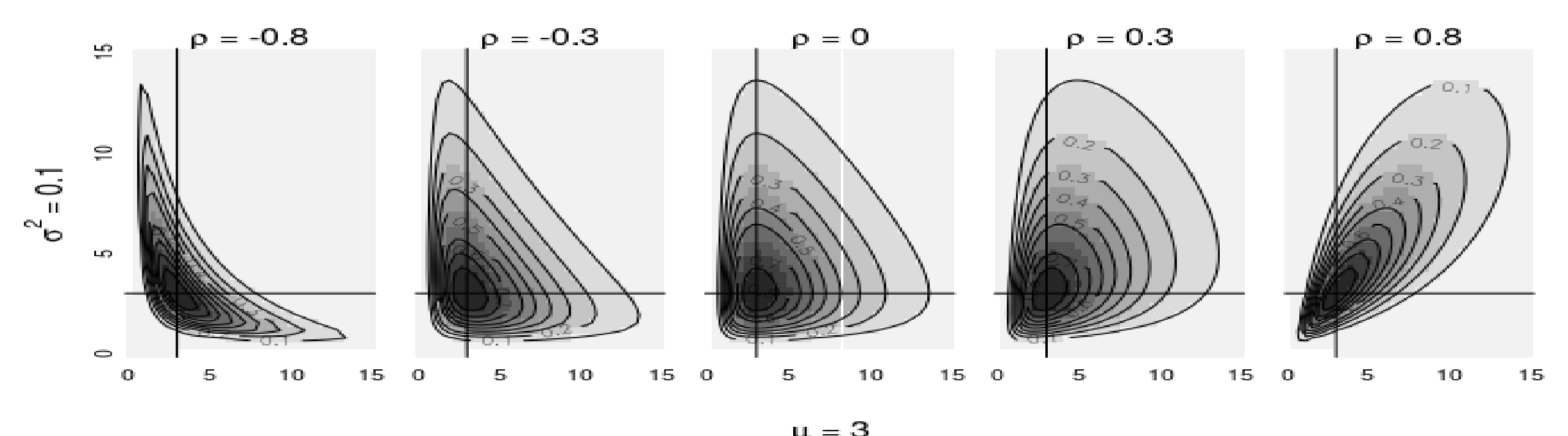


Figure 5: Core of the non-normalized bivariate inverse Normal distribution.

- Interpretation
- The parameter ρ controls the correlation.
 - The dispersion parameters control the variability and shape.
 - Similar to the bivariate normal distribution.
 - $\boldsymbol{\mu}$ is not necessarily a vector of expectations: better interpreted as a vector of modes.

Conclusions and discussion

- The method is simple and the interpretation is intuitive.
- Results about the normalizing constants do not influence directly on the construction of regression models for the location parameters.

Future work includes:

- Evaluate the approximations to the normalizing constants.
- Inference and full computational implementation.

Bibliography

- Jørgensen, Bent. *The Theory of Dispersion Models*, 1987
- Bent Jørgensen and Steffen L. Lauritzen *Multivariate Dispersion Models*.2000.
- R Core Team *R: A Language and Environment for Statistical Computing*.2018.